

## \* BEST FIRST SEARCH :-

- Best - first Search algorithm always selects the Path which appears best at the moment.
- It is the combination of depth - first search and breadth - first search algorithm.
- Best First Search falls under the category of Heuristic search or informed search.
- The aim is to reach the goal from the initial state via the shortest path.
- It is implemented by the priority Queue.
- In BFS, we expand the node which is closest to the goal node.  
The "closeness" is estimated by heuristic  $h(n)$ .

→ Algorithm :-

- Step 1:- Place the starting node into the OPEN list.
- Step 2:- If the OPEN list is empty, stop and return failure

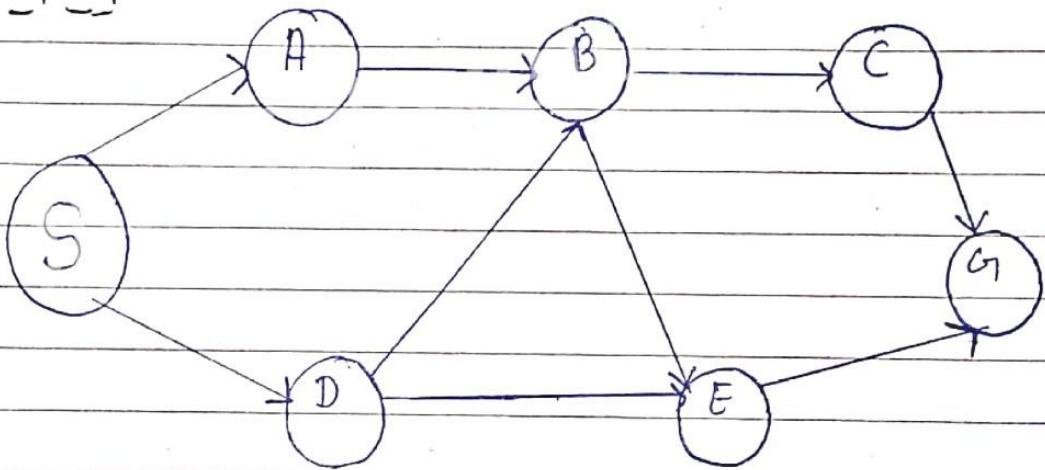


Step 3:- Remove the node  $n$ , from the OPEN list which has the lowest value. and places it in CLOSED list.

Step 4:- Expand the node  $n$ , and generate the successors of node  $n$ .

Step 5:- Check each successor of node  $n$ , and find whether any node is a goal node or not.

→ Example:



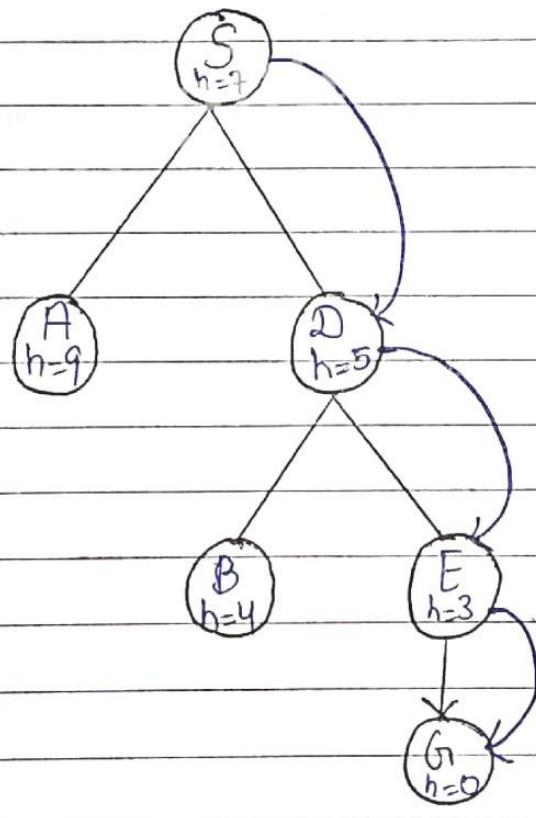
node	$H(n)$
A	9
B	4
C	2
D	5
E	3
S	7
G	0



Solution:- Starting from S, we can traverse to A ( $h=9$ ) or D ( $h=5$ ). We choose D, as it has lower heuristic cost.

- Now from D, we can move to B ( $h=4$ ) or E ( $h=3$ ). We choose E with lower cost.
- Finally from E, we go to G<sub>1</sub> ( $h=0$ ).

Path :-  $S \rightarrow D \rightarrow E \rightarrow G_1$



Initialization :-

Open [A,D], Closed [S]

Iteration 1: Open [A],  
Closed [S,D]

Iteration 2: Open [A,B,E]  
Closed [S,D]  
: Open [A,B]  
Closed [S,D,E]

Iteration 3: Open [A,B]  
Closed [S,D,E,G<sub>1</sub>]

Hence the final solution :-  $S \rightarrow D \rightarrow E \rightarrow G_1$

- Advantages:-

- It takes fewer steps to reach a goal.
- The algorithm is more efficient than BFS and DFS algorithms.

- Disadvantages:-

- It can turn into unguided DFS in the Worst Case.